Problems of Harmonic Analysis related to finite type hypersurfaces in 3 space

Detlef Müller joint work with I. Ikromov, and I. Ikromov - M. Kempe

Analysis and Applications: A Conference in Honor of Elias M. Stein Princeton, May 16-20, 2011

## Introduction: Three inter-related problems

S = smooth, finite type hypersurface in  $\mathbb{R}^3$ ,

 $d\mu:=
ho d\sigma, \ d\sigma:=$  surface measure on  $S, \ 0\leq
ho\in C_0^\infty(S)$ 

## A

Sharp uniform decay estimates for  $\widehat{d\mu}(\xi) := \int_S e^{-i\xi x} d\mu(x), \ \xi \in \mathbb{R}^3$  ?

#### В

 $L^{p}(\mathbb{R}^{3})$  - boundedness of the maximal operator  $\mathcal{M}f(x) := \sup_{t>0} |A_{t}f(x)|$ , where  $A_{t}f(x) := \int_{S} f(x - ty) d\mu(y)$ .

$$\left(\int_{S} |\hat{f}(x)|^2 d\mu(x)\right)^{1/2} \le C \|f\|_{L^p(\mathbb{R}^3)}, \quad f \in \mathcal{S}(\mathbb{R}^3) ?$$

#### 3 Problems History

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## Short History of these problems

(A) Estimation of oscillatory integrals:

B. Riemann (1854): appear implicitly in his work Best understood: Convex hypersurfaces of finite line type: B. Randol (1969) I. Svensson(1971) H. Schulz (1991) J. Bruna, A. Nagel, S. Wainger (1988) Non-convex case: A.N. Varchenko (1976) :  $\int e^{i\lambda\phi(x_1,x_2)}a(x_1,x_2) dx$ ,  $\phi$  analytic V.N. Karpushkin (1984):  $\int e^{i\lambda(\phi(x_1,x_2)+r(x_1,x_2))}a(x_1,x_2) dx$ ,  $\phi$  analytic

(C) The Fourier-restriction problem: E.M. Stein (1967).
 E.M. Stein and P.A. Tomas (1975) :

$$\Big(\int_{S^{n-1}} |\hat{f}(x)|^2 \, d\mu(x)\Big)^{1/2} \leq C \|f\|_{L^p(\mathbb{R}^n)}$$

iff  $p' \ge 2(\frac{2}{n-1}+1)$ .

#### (B) Maximal functions associated to hypersurfaces in $\mathbb{R}^n$ :

E.M. Stein (1976)
J. Bourgain (1986)
A. losevich ('94); Marletta('94):
C. Sogge, E.M: Stein ('85):
Best understood case:
Contributions e.g. by:

spheres in  $\mathbb{R}^n$ ,  $n \ge 3$  (p > n/(n-1)). circle in  $\mathbb{R}^2$ , (p > 2). finite type curves partial results if K = 0 somewhere convex hypersurfaces of finite line type M. Cowling and G. Mauceri ('86/87), A. Nagel, A. Seeger, S. Wainger ('93), A. losevich, E. Sawyer, A, Seeger ('99)

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#### **Representation of** *S* **as a graph of** $\phi$

 $S \subset \mathbb{R}^3$  smooth, finite type hypersurface;  $x^0 \in S$  :

By localization near  $x^0$  and application of Euclidean motion of  $\mathbb{R}^3$  we may assume:  $x^0 = (0, 0, 0)$ , and

$$S = \{(x_1, x_2, \phi(x_1, x_2)) : (x_1, x_2) \in \Omega\},\$$

where  $\phi \in C^\infty(\Omega)$  s.t.  $\phi(0,0) = 0, \, \nabla \phi(0,0) = 0.$  If

$$\phi(x_1, x_2) \sim \sum_{j,k=0}^{\infty} c_{jk} x_1^j x_2^k$$

is the Taylor series of  $\phi$ , define the Taylor support of  $\phi$  at (0,0) by

$$\mathcal{T}(\phi) := \{(j,k) \in \mathbb{N}^2 : c_{jk} \neq 0\}.$$

NOTICE:  $\mathcal{T}(\phi) \neq \emptyset$ , since  $\phi$  is of finite type at the origin!

$$\mathcal{N}(\phi) := \operatorname{conv} \bigcup_{(j,k)\in\mathcal{T}(\phi)} (j,k) + \mathbb{R}^2_+$$

- Newton distance : d = d(\u03c6) is given by the coordinate d of the point (d, d) at which the bisectrix t<sub>1</sub> = t<sub>2</sub> intersects the boundary of the Newton polyhedron.
- Principal face π(φ) : The face of minimal dimension containing the point (d, d).
- In Principal part of  $\phi$ :

$$\phi_{\mathrm{pr}}(x_1, x_2) := \sum_{(j,k) \in \pi(\phi)} c_{jk} x_1^j x_2^k$$

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## Figure 1



Figure: Newton polyhedron

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## Adapted coordinates Height of $\phi$ :

 $h(\phi) := \sup\{d_x\},\$ 

where the supremum is taken over all local analytic (resp. smooth) coordinate systems x at the origin, and where  $d_x$  is the Newton distance of  $\phi$  when expressed in the coordinates x.

NOTICE: The height is invariant under local smooth changes of coordinates at the origin!

A coordinate system x is said to be adapted to  $\phi$  if  $h(\phi) = d_x$ .

Example. Let

$$\phi(x_1, x_2) := (x_2 - x_1^m)^n + x_1^{\ell}.$$

If  $\ell > mn$ , the coordinates are not adapted. Adapted coordinates are then  $y_1 := x_1, y_2 := x_2 - x_1^m$ , in which  $\phi$  is given by

$$\phi^a(y) = y_2^n + y_1^\ell.$$

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## Example 1



Figure:  $\phi(x_1, x_2) := (x_2 - x_1^m)^n + x_1^\ell \quad (\ell > mn)$ 

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#### **Edges and homogeneities**

Let  $\kappa = (\kappa_1, \kappa_2)$  with, say,  $\kappa_2 \ge \kappa_1 > 0$ , be a given weight, with corresponding dilations

$$\delta_r(x_1, x_2) := (r^{\kappa_1}x_1, r^{\kappa_2}x_2), \quad r > 0.$$

F on  $\mathbb{R}^2$  is  $\kappa$ -homogeneous of degree a, (short: mixed homogeneous ) if

$$F(\delta_r x) = r^a F(x) \quad \forall r > 0, x \in \mathbb{R}^2.$$

Choose *a* so that  $L_{\kappa} := \{(t_1, t_2) \in \mathbb{R}^2 : \kappa_1 t_1 + \kappa_2 t_2 = a\}$  is the supporting line to the Newton polyhedron  $\mathcal{N}(\phi)$  of  $\phi$ . The  $\kappa$ -principal part of  $\phi$ 

$$\phi_\kappa(x_1,x_2) := \sum_{(j,k)\in L_\kappa} c_{jk} x_1^j x_2^k$$

is  $\kappa$ -homogeneous of degree a.

 $\phi(x_1, x_2) = \phi_{\kappa}(x_1, x_2) + \text{ terms of higher } \kappa\text{-degree.}$ 

NOTICE: If the principal face  $\pi(\phi)$  is an edge, then there is a unique weight  $\kappa = \kappa_{\rm pr}$  so that  $\pi(\phi)$  lies on the line  $\kappa_1 t_1 \pm \kappa_2 t_2 = 1$ .

#### **Adaptedness**

Let  $P \in \mathbb{R}[x_1, x_2]$  be a  $\kappa$ - homogeneous polynomial with  $\nabla P(0, 0) = 0$ , let

 $m(P) := \operatorname{ord}_{S^1} P$ 

be the maximal order of vanishing of P along the unit circle  $S^1$  centered at the origin.

Theorem (Varchenko; Phong, J. Sturm, Stein (analytic  $\phi$ ); I.,M.)

There always exist adapted smooth coordinates y, of the form  $y_1 = x_1$ ,  $y_2 = x_2 - \psi(x_1)$ .

## Theorem (Condition for non-adaptedness)

The coordinates x are not adapted to  $\phi$  if and only if the principal face  $\pi(\phi)$  of the Newton polyhedron  $\mathcal{N}(\phi)$  is a compact edge, and  $m(\phi_{\mathrm{pr}}) > d(\phi)$ . Moreover, the latter implies that  $\frac{\kappa_2}{\kappa_1} \in \mathbb{N}$ , where  $\kappa := \kappa_{\mathrm{pr}}$ .

#### A. Decay of the Fourier transform of the surface measure

Varchenko's exponent  $\nu(\phi) \in \{0,1\}$ : If there exists an adapted local coordinate system y near the origin such that the principal face  $\pi(\phi^a)$  of  $\phi$ , when expressed by the function  $\phi^a$  in the new coordinates (i.e.  $\phi(x) = \phi^a(y)$ ), is a vertex, and if  $h(\phi) \ge 2$ , then we put  $\nu(\phi) := 1$ ; otherwise, we put  $\nu(\phi) := 0$ .

#### Theorem

Let  $S = \operatorname{graph}(\phi)$  be as before. Then there exists a neighborhood  $U \subset S$  of  $x^0 = 0$  such that for every  $\rho \in C_0^{\infty}(U)$  the following estimate holds true for every  $\xi \in \mathbb{R}^3$ :

$$|\widehat{d\mu}(\xi)| \le C \, \|\rho\|_{C^3(S)} \, (\log(2+|\xi|))^{\nu(\phi)} (1+|\xi|)^{-1/h(\phi)} \tag{3.1}$$

#### **Remarks:**

- In the analytic setting, this is due to V.N. Karpushkin.
- **2** For  $\phi$  smooth, M. Greenblatt had obtained such estimates for  $\xi$  normal to S at 0.

#### Sharpness

Let *N* be a unit normal to *S* at  $x^0 = 0$ , and put

$$J(\lambda) := \widehat{d\mu}(\lambda N) = \iint e^{\pm i\lambda\phi(x_1,x_2)} a(x_1,x_2) \, dx_1 dx_2, \quad \lambda > 0.$$

#### Proposition

If in an adapted coordinates system the principal face  $\pi(\phi^a)$  is a compact set (i.e. a compact edge or a vertex), then the following limit

$$\lim_{\lambda \to +\infty} \frac{\lambda^{1/h(\phi)}}{\log \lambda^{\nu(\Phi)}} J(\lambda) = C \cdot a(0,0),$$

exists, where C is a non-zero constant depending on  $\phi$  only.

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#### **Remarks:**

- This improves on a result by M. Greenblatt, who proved that this limit exists for some sequence of λ<sub>k</sub> → ∞.
- If the principal face π(φ<sup>a</sup>) is unbounded, then the estimate in the theorem may fail to be sharp, if φ is non-analytic, as the following example by A. Iosevich and E. Sawyer shows: If

$$\Phi(x_1, x_2) := x_2^2 + e^{-1/|x_1|^{\alpha}},$$

then

$$|J(\lambda)| symp rac{1}{\lambda^{1/2}\log\lambda^{1/lpha}} \quad ext{as} \quad \lambda o +\infty.$$

Here,  $\nu(\phi) = 0$ .

## B. Sharp estimates for the maximal operator $\ensuremath{\mathcal{M}}$

- Translations do not commute with dilations.
- $\implies$  Euclidean motions are no admissible coordinate changes for the study of the maximal operators  $\mathcal{M}$ .

## Transversality Assumption:

The affine tangent plane  $x + T_x S$  to S through x does not pass through the origin in  $\mathbb{R}^3$  for every  $x \in S$ . Equivalently,  $x \notin T_x S$  for every  $x \in S$ , so that  $0 \notin S$ , and x is transversal to S for every point  $x \in S$ .

 $\implies$  If  $x^0 \in S$ , then there is a **linear** change of coordinates in  $\mathbb{R}^3$  so that in the new coordinates  $x^0 = 0$ , and S is locally given by

$$S = graph(1 + \phi)$$
  $(\phi(0, 0) = 0, \nabla \phi(0, 0) = 0).$ 

Put

$$h(x^0,S):=h(\phi)$$

This notion is invariant under affine linear changes of coordinates in the ambient space  $\mathbb{R}^3$ !

#### **Maximal estimates**

Let  $S \subset \mathbb{R}^3$  be a hypersurface as before, and  $x^0 \in S$ . Recall that

$$A_t f(x) := \int_S f(x - ty) \rho(y) \, d\sigma(y), \quad t > 0,$$
  
$$\mathcal{M}f(x) := \sup_{t > 0} |A_t f(x)|.$$

## Theorem (Boundedness of $\mathcal{M}$ for p > 2)

- (i) Assume that p > 2. If the measure ρdσ is supported in a sufficiently small neighborhood of x<sup>0</sup>, then M is bounded on L<sup>p</sup>(ℝ<sup>3</sup>) whenever p > h(x<sup>0</sup>, S).
- (ii) If  $\mathcal{M}$  is bounded on  $L^p(\mathbb{R}^3)$  for some p > 1, and if  $\rho(x^0) > 0$ , then  $p \ge h(x^0, S)$ . Moreover, if S is analytic at  $x^0$ , then  $p > h(x^0, S)$ .

## Order of contact with hyperplanes

• *H* affine hyperplane:  $d_H(x) := \operatorname{dist}(H, x)$ .

## Theorem (losevich-Sawyer)

If the maximal operator  $\mathcal{M}$  is bounded on  $L^p(\mathbb{R}^n)$ , where p > 1, then

$$\int_{S} d_{H}(x)^{-1/p} \rho(x) d\sigma(x) < \infty$$
(4.2)

for every affine hyperplane H in  $\mathbb{R}^n$  which does not pass through the origin.

#### Conjecture (losevich-Sawyer)

For p > 2 condition (4.2) is necessary and sufficient for the boundedness of  $\mathcal{M}$  on  $L^p$ .

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#### Theorem

Assume that  $S \subset \mathbb{R}^3$  is as before, and  $\rho$  is supported in a sufficiently small neighborhood of  $x^0$ . If S is analytic, then the conjecture of losevich-Sawyer holds true, and if S is only of finite type, then it is true, with the possible exception of the exponent  $p = h(x^0, S)$ .

#### Oscillation, order of contact and sublevel estimates

Given  $x^0 \in S$ , call

**Q** uniform oscillation index  $\beta_u(x^0)$ : the supremum over all  $\beta$  s.t.

$$|\widehat{\rho d\sigma}(\xi)| \le C_{\beta} \left(1 + |\xi|\right)^{-\beta} \qquad \forall \xi \in \mathbb{R}^{n}$$
(4.3)

for all  $\rho$  supported in a sufficiently small neighborhood of  $x^0$ . uniform contact index  $\gamma_u(x^0)$ : the supremum over all  $\gamma$  s.t.

$$\int_{S} d_{H}(x)^{-\gamma} \rho(x) \, d\sigma(x) < \infty \tag{4.4}$$

for every affine hyperplane H and  $\rho$  as before.

If we restrict directions to the normal to S in x<sup>0</sup>, respectively H to the affine tangent plane in x<sup>0</sup>, we introduce accordingly the oscillation index β(x<sup>0</sup>) and the contact index γ(x<sup>0</sup>).

## Combining our results with results by Phong, Stein and Sturm, we get

Theorem

Let  $x^0 \in S \subset \mathbb{R}^3$  be a fixed point. Then

$$\beta_u(x^0, S) = \beta(x^0, S) = \gamma_u(x^0, S) = \gamma(x^0, S) = 1/h(x^0, S).$$

Note: The contact order estimates are essentially equivalent to certain sublevel estimates (Tschebychev!)

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#### The case $p \le 2$

- If p ≤ 2, then neither the notion of height nor that of contact index will determine the range of exponents p for which the maximal operator M is L<sup>p</sup>-bounded.
- We have a conjecture for this case, which for certain surfaces relates to fundamental open problems in Fourier analysis, such as the conjectured reverse square function estimate for the cone multiplier
- Work in progress!

# C. Fourier restriction: Adapted coordinates

We may assume that

$$S = \{(x_1, x_2, \phi(x_1, x_2)) : (x_1, x_2) \in \Omega\}, \quad x^0 = 0.$$

#### Theorem

Assume that the coordinates  $(x_1, x_2)$  are adapted to  $\phi$ , where  $\phi$  is smooth of finite type. If the support of  $\rho \ge 0$  is contained in a sufficiently small neighborhood of 0, then

$$\left(\int_{\mathcal{S}}|\widehat{f}|^{2}\rho d\sigma\right)^{1/2} \leq C_{p}\|f\|_{L^{p}(\mathbb{R}^{3})}, \qquad f \in \mathcal{S}(\mathbb{R}^{3}), \tag{5.1}$$

for every  $p \ge 1$  such that  $p' \ge 2h(\phi) + 2$ .

## Remarks:

Knapp type examples show that our result is sharp.

A. Magyar had obtained partial results in the analytic case before.

### On the proof

For p' > 2h(φ) + 2, this follows directly from our Fourier decay estimate (3.1) and

Theorem (Greenleaf '81 - the case n = 3)

Assume that  $\widehat{d\mu}(\xi) \lesssim |\xi|^{-1/h}$ . Then the restriction estimate

$$\left(\int_{\mathcal{S}}|\widehat{f}|^2\,d\mu\right)^{1/2}\leq C_p\|f\|_{L^p(\mathbb{R}^3)}$$

holds for every  $p \ge 1$  such that  $p' \ge 2h + 2$ .

The endpoint p' = 2h(\u03c6) + 2 can be obtained by Littlewood-Paley theory.

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## C. Fourier restriction: Non-adapted coordinates

Then  $\pi(\phi)$  is a compact edge, lying on a unique line

$$L := \{ (t_1, t_2) \in \mathbb{R}^2 : \kappa_1 t_1 + \kappa_2 t_2 = 1 \}.$$

Moreover,

$$m := \kappa_2 / \kappa_1 \in \mathbb{N}, \quad \text{(and } m \ge 2\text{)}, \tag{5.2}$$

and  $m(\phi_{\rm pr}) > d(\phi)$ , so that there is (exactly) one real root  $x_2 = b_1 x_1^m$  of  $\phi_{\rm pr}$  of multiplicity bigger than  $h(\phi)$ , the principal root. Changing coordinates

$$y_1 := x_1, \ y_2 := x_2 - b_1 x_1^m,$$

we arrive at a "better" coordinate system *y*. By iterating this procedure, we arrive at Varchenko's algorithm for constructing an adapted coordinate system (in higher dimension, adapted coordinates may not exist!).

In the end, one can find a change of coordinates

$$y_1 := x_1, \ y_2 := x_2 - \psi(x_1)$$
 (5.3)

leading to adapted coordinates y for  $\phi,$  where the principal root jet  $\psi$  has a Taylor approximation

$$\psi(x_1) = b_1 x_1^m + O(x_1^{m+1}).$$

In the adapted coordinates  $y, \phi$  is given by

 $\phi^{\boldsymbol{a}}(\boldsymbol{y}) := \phi(\boldsymbol{y}_1, \boldsymbol{y}_2 + \psi(\boldsymbol{y}_1)).$ 

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## Newton polyhedron $\mathcal{N}(\phi^a)$



Figure: Edges and weights

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#### m-Height

Consider the line parallel to the bi-sectrix

$$\Delta^{(m)}:=\{(t,t+m+1):t\in\mathbb{R}\}.$$

For any edge  $\gamma_\ell \subset L_\ell := \{(t_1, t_2) \in \mathbb{R}^2 : \kappa_1^\ell t_1 + \kappa_2^\ell t_2 = 1\}$  define  $h_\ell$  by  $\Delta^{(m)} \cap L_\ell = \{(h_\ell - m, h_\ell + 1)\},$ 

i.e.

$$h_{\ell} = \frac{1 + m\kappa_1^{\ell} - \kappa_2^{\ell}}{\kappa_1^{\ell} + \kappa_2^{\ell}},$$
(5.4)

and define the m-height of  $\phi$  by

$$h^{(m)}(\phi) := \max(d, \max_{\ell:a_{\ell} > m} h_{\ell}).$$

#### **Remarks:**

- For *L* in place of  $L_{\ell}$ , one has  $m = \kappa_2/\kappa_1$  and  $d = 1/(\kappa_1 + \kappa_2)$ , so that one gets *d* in place of  $h_{\ell}$  in (5.4)
- 3 Since  $m < a_\ell$ , we have  $h_\ell < 1/(\kappa_1^\ell + \kappa_2^\ell)$ , hence  $h^{(m)}(\phi) < h(\phi)$ .

## m-height $h^{(m)}(\phi)$



#### Figure: m-height

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## Theorem

Assume that there is no linear coordinate system adapted to  $\phi$ , where  $\phi$  is smooth of finite type. Then there exists a neighborhood  $U \subset S$  of  $x^0 = 0$  such that for every non-negative density  $\rho \in C_0^{\infty}(U)$ ,

$$\left(\int_{\mathcal{S}}|\widehat{f}|^{2}\rho d\sigma\right)^{1/2} \leq C_{\rho}\|f\|_{L^{\rho}(\mathbb{R}^{3})}, \qquad f \in \mathcal{S}(\mathbb{R}^{3}), \tag{5.5}$$

for every  $p \ge 1$  such that  $p' > p'_c := 2h^{(m)}(\phi) + 2$ .

#### Remarks:

- The condition  $p' > 2p'_c + 2$  is weaker than the condition  $p' > 2h(\phi) + 2$ , which would follow from Greenleaf's result!
- Again, Knapp type examples show that our result is sharp, except possibly for the endpoint.
- If  $\phi$  analytic, presumably true also at endpoint  $p = p_c$ .

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### Example 2

$$\phi(x_1, x_2) := (x_2 - x_1^m)^n, \qquad n, m \ge 2.$$

The coordinates  $(x_1, x_2)$  are not adapted. Adapted coordinates are  $y_1 := x_1, y_2 := x_2 - x_1^m$ , in which  $\phi$  is given by

 $\phi^a(y_1,y_2)=y_2^n.$ 

Here

$$\kappa_1 = \frac{1}{mn}, \quad \kappa_2 = \frac{1}{n},$$
  
$$d := d(\phi) = \frac{1}{\kappa_1 + \kappa_2} = \frac{nm}{m+1},$$

and

$$p'_{c} = \begin{cases} 2d+2, & \text{if } n \leq m+1, \\ 2n, & \text{if } n > m+1. \end{cases}$$

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## Example 2



Figure:  $\phi(x_1, x_2) := (x_2 - x_1^m)^n \quad (n, m \ge 2)$ 

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## BASIC INGREDIENCES OF PROOFS (Maximal Estimate)

| Puiseux expansion of roots and Newton polyhedra. Assume  $\phi$  analytic:

$$\phi(x_1, x_2) = U(x_1, x_2) x_1^{\nu_1} x_2^{\nu_2} \prod_r (x_2 - r(x_1)), \quad U(0, 0) \neq 0;$$

roots  $r(x_1)$  admit a Puiseux series expansion

$$r(x_1) = c_{l_1}^{\alpha_1} x_1^{a_{l_1}} + c_{l_1 l_2}^{\alpha_1 \alpha_2} x_1^{a_{l_1 l_2}^{\alpha_1}} + \dots + c_{l_1 \dots l_p}^{\alpha_1 \dots \alpha_p} x_1^{a_{l_1 \dots l_p}^{\alpha_1 \dots \alpha_{p-1}}} + \dots;$$

▶ exponents a<sup>α1...αp-1</sup><sub>l<sub>1</sub>...l<sub>p</sub></sub> > 0 are all multiples of a fixed rational;
 ▶ c<sup>α1...αp</sup><sub>l<sub>1</sub>...l<sub>p</sub></sub> ∈ ℂ \ {0}.
 ▶

$$a_1 < \cdots < a_\ell < \cdots < a_n$$

the distinct leading exponents of all the roots r.

**Phong and Stein:** Group the roots into clusters  $[\ell]$  consisting of all roots with leading exponent  $a_{\ell}$ . Each cluster  $[\ell]$  is associated to an edge  $\gamma_{\ell}$  of  $\mathcal{N}(\phi)$ .

The ("easy") case when the coordinates are adapted to  $\phi$  (e.g. if  $\phi$  convex)

## Decomposition

 $\phi = \phi_{\rm pr} \ + \ {\rm error},$ 

where  $\phi_{\rm pr}$  is  $\kappa$ -homogeneous (if  $\phi$  is convex and finite line type,  $\phi_{\rm pr}$  is just the **Schulz polynomial!**). We can then basically reduce to assuming  $\phi_{\rm pr} = \phi_{\kappa}$ .

- Dyadic decomposition and re-scaling of dyadic pieces using dilations δ<sub>r</sub> associated to the weight κ.
- Control of multiplicity of roots on dyadic pieces:  $\forall x^0$  with  $|x^0| \sim 1$  there is a direction *e* such that

$$\partial_e^m \phi_{\mathrm{pr}}(x_1^0, x_2^0) \neq 0 \text{ for some } 2 \leq m \leq h(\phi).$$

• This leads to the right control of oscillatory integrals (van der Corput!) or maximal operators , e.g. by reduction to curves:

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**II** Decomposition of *S* into families of curves, e.g. fan decomposition:



#### Figure: Fan Decomposition

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#### The case when the coordinates are not adapted to $\phi$

- **III** Domain decomposition (no damping technics!)
  - γ<sub>1</sub>, γ<sub>2</sub>,..., edges of N(φ<sup>a</sup>) above principal edge, with associated weights κ<sup>ℓ</sup>.

Decompose  $\Omega$  into  $\kappa^{\ell}$ -homogeneous domains  $D_{\ell}$  containing the cluster of non-trivial roots of  $\phi^a_{\kappa^{\ell}}$  associated to  $\gamma_{\ell}$  (these roots have multiplicity bounded by  $1/(\kappa^{\ell}_1 + \kappa^{\ell}_2) < h(\phi)$ , since they are away from the principal root jet) and the "transition domains"  $E_{\ell}$  between these domains, which have no homogeneous structure.

- For the domains  $D_{\ell}$ , one can argue somewhat similarly as in the adapted case, but we also need control on multiplicities of roots of  $\partial_2 \phi_{\rm pr}^a$  and  $\partial_2^2 \phi_{\rm pr}^a$ .
- For the transition domains E<sub>ℓ</sub>, use bi-dyadic decomposition into rectangles, re-scale, and again reduce, e.g., to maximal averages along curves.

#### **Clusters of roots**



#### Figure: Clusters of roots

## What is left?

- A small,  $\kappa^a$ -homogenous (in the adapted coordinates) neighborhood of the principal root jet  $\psi$  which can no longer be dealt with by maximal averages along curves.
- In this domain, in adapted coordinates, the total multiplicity of all roots is controlled by the homogeneous dimension  $1/(\kappa_1^a + \kappa_2^a)$  of the principal edge.
- Main Problem: If  $\partial_2^j \phi_{\mathrm{pr}}^a(y^0) = 0, \ j = 1, \dots, h.$
- To overcome this, e.g. for *M* we apply a further domain decomposition by means of a stopping time argument into homogeneous domains D'<sub>ℓ</sub> and transition domains E'<sub>ℓ</sub>, oriented at the level sets of ∂<sub>2</sub>φ<sup>a</sup>, which again are chopped up into dyadic resp. bi-dyadic pieces.
- After re-scaling, the contributions of these pieces can eventually be estimated by oscillatory integral technics in 2 variables.

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#### Oscillatory integrals with small parameters $\delta, \sigma$

Problem: Oscillatory integrals with small parameters We need **uniform estimates** of oscillatory integrals of the form

$$J(\xi) = \iint_{\mathbb{R}^2} e^{i(\xi_1 y_1 + \xi_2 \psi(y_1) + \xi_2 y_2 + \xi_3 \phi^*(y))} \eta(y) \, dy,$$

where  $\phi^a$  and  $\psi$  depend on **small parameters** and where the interplay between these functions is crucial.

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#### Degenerate Airy type

Most difficult situation: Oscillatory integrals of degenerate Airy type

$$J(\lambda,\sigma,\delta) := \int_{\mathbb{R}^2} e^{i\lambda F(x,\sigma,\delta)} \psi(x,\delta) \, dx,$$

with  $F(x_1, x_2, \sigma, \delta) := f_1(x_1, \delta) + \sigma f_2(x_1, x_2, \delta).$ 

Example (The following  $\phi$  leads to such oscillatory integrals)

$$\phi(x_1, x_2) := (x_2 - x_1^m)^{\ell} + x_2 x_1^{n-m}$$

where  $n/\ell > m \ge 2$ . Here,  $\psi(x_1) := x_1^m$ ,

$$\phi^{a}(y_{1}, y_{2}) = y_{1}^{n} + y_{2}^{\ell} + y_{2}y_{1}^{n-m},$$

and

$$\phi_{\mathrm{pr}}^{a}(y_1, y_2) = y_1^{n} + y_2^{\ell}.$$

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#### Theorem

Assume that

$$|\partial_1 f_1(0,0)| + |\partial_1^2 f_1(0,0)| + |\partial_1^3 f_1(0,0)| \neq 0$$

and  $\partial_1 \partial_2 f_2(0,0,0) \neq 0$ , and that there is some  $m \geq 2$  such that

$$\partial_2^l f_2(0,0,0) = 0$$
 for  $l = 1, \dots, m-1$ 

and  $\partial_2^m f_2(0,0,0) \neq 0$ .

Then there exist a neighborhood  $U \subset \mathbb{R}^2$  of the origin and constants  $\varepsilon, \varepsilon' > 0$  such that for any  $\psi$  which is compactly supported in U

$$|J(\lambda,\sigma,\delta)| \leq \frac{C \|\psi(\cdot,\delta)\|_{C^3}}{\lambda^{\frac{1}{2}+\varepsilon} |\sigma|^{(l_m+c_m\varepsilon),}}$$

uniformly for  $|\sigma| + |\delta| < \varepsilon'$ , where  $l_m := \frac{1}{6}$  and  $c_m := 1$  for m < 6, and  $l_m := \frac{m-3}{2(2m-3)}$  and  $c_m := 2$  for  $m \ge 6$ .

## THANKS FOR YOUR ATTENTION!

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